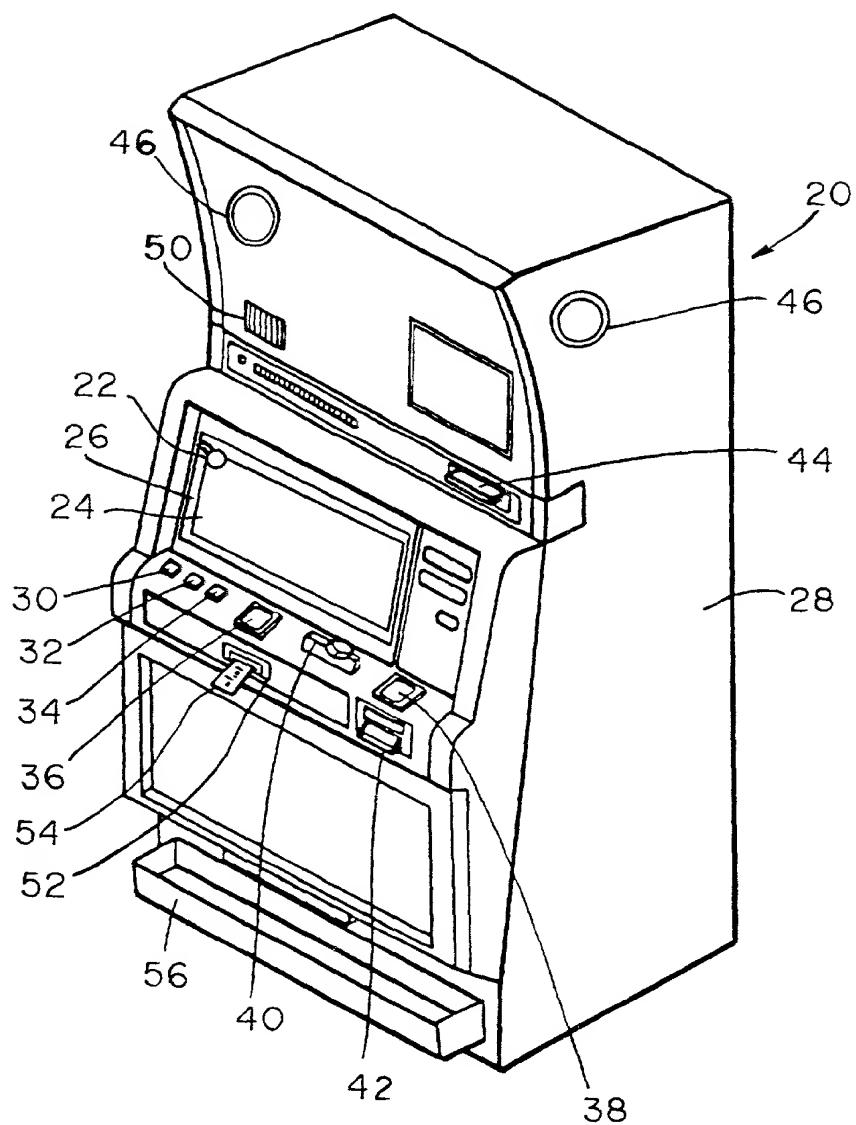


FIG. 1



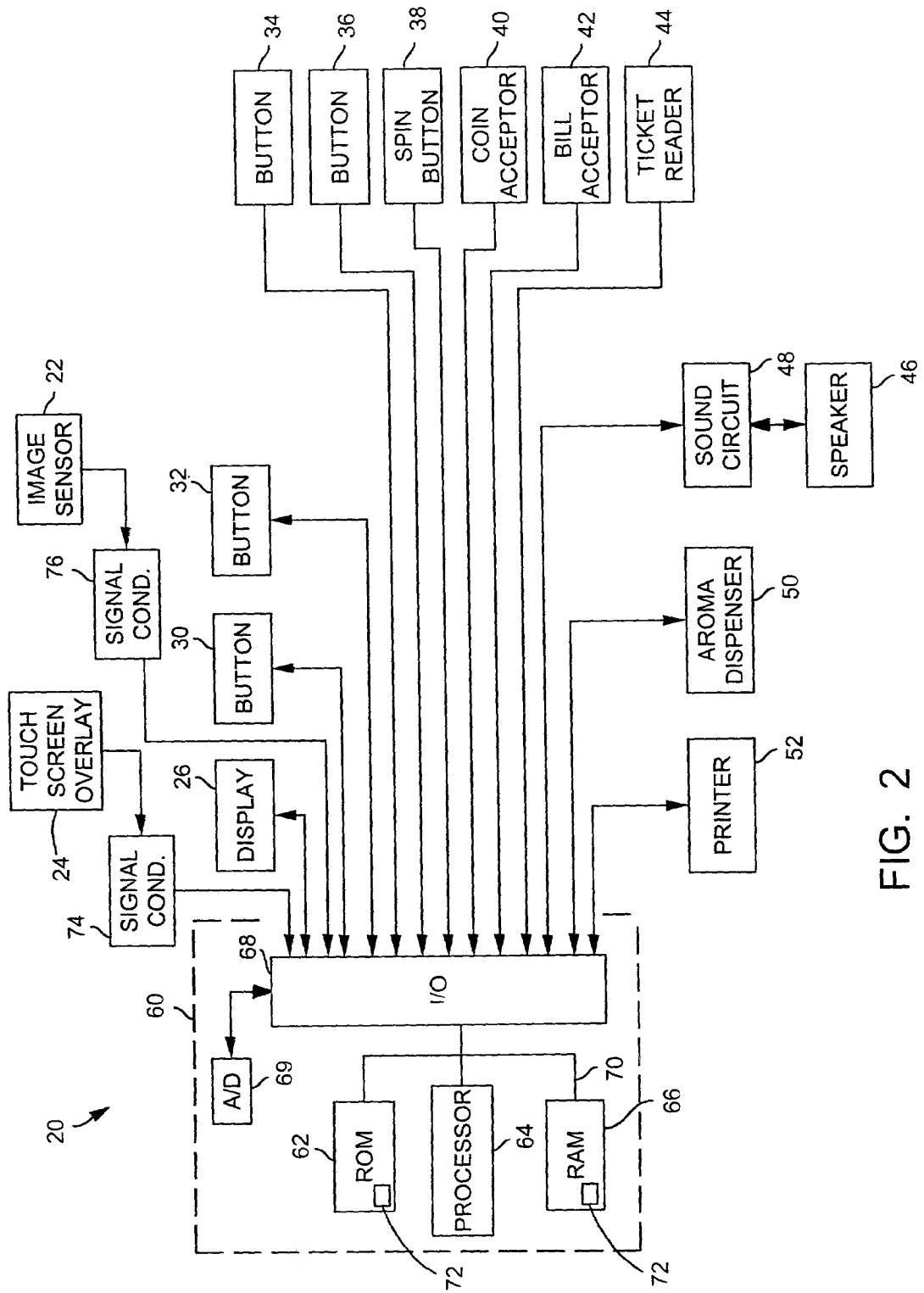


FIG. 2

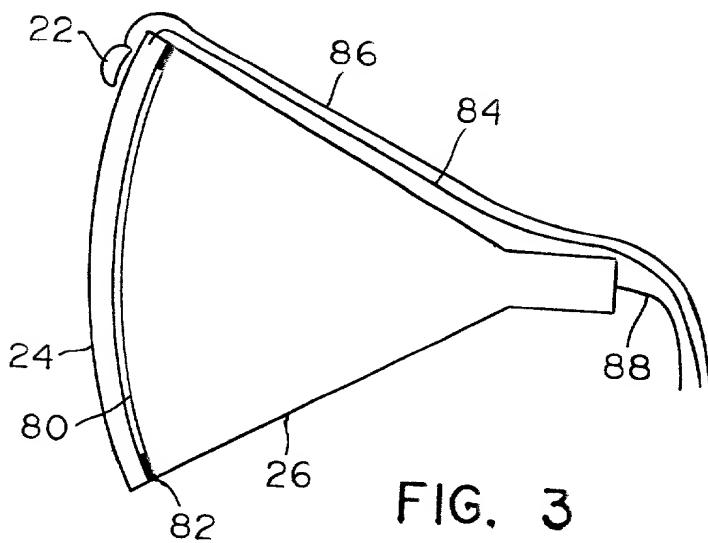


FIG. 3

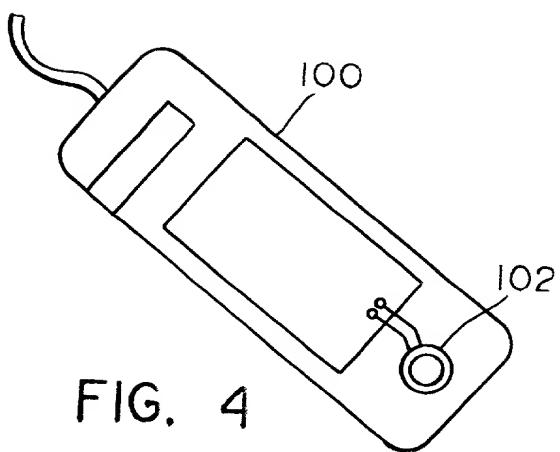


FIG. 4

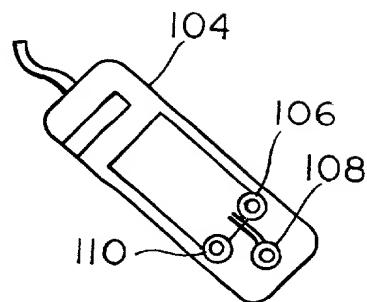


FIG. 5

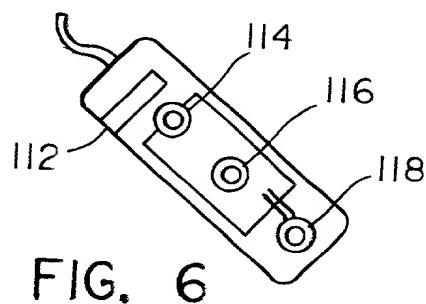


FIG. 6

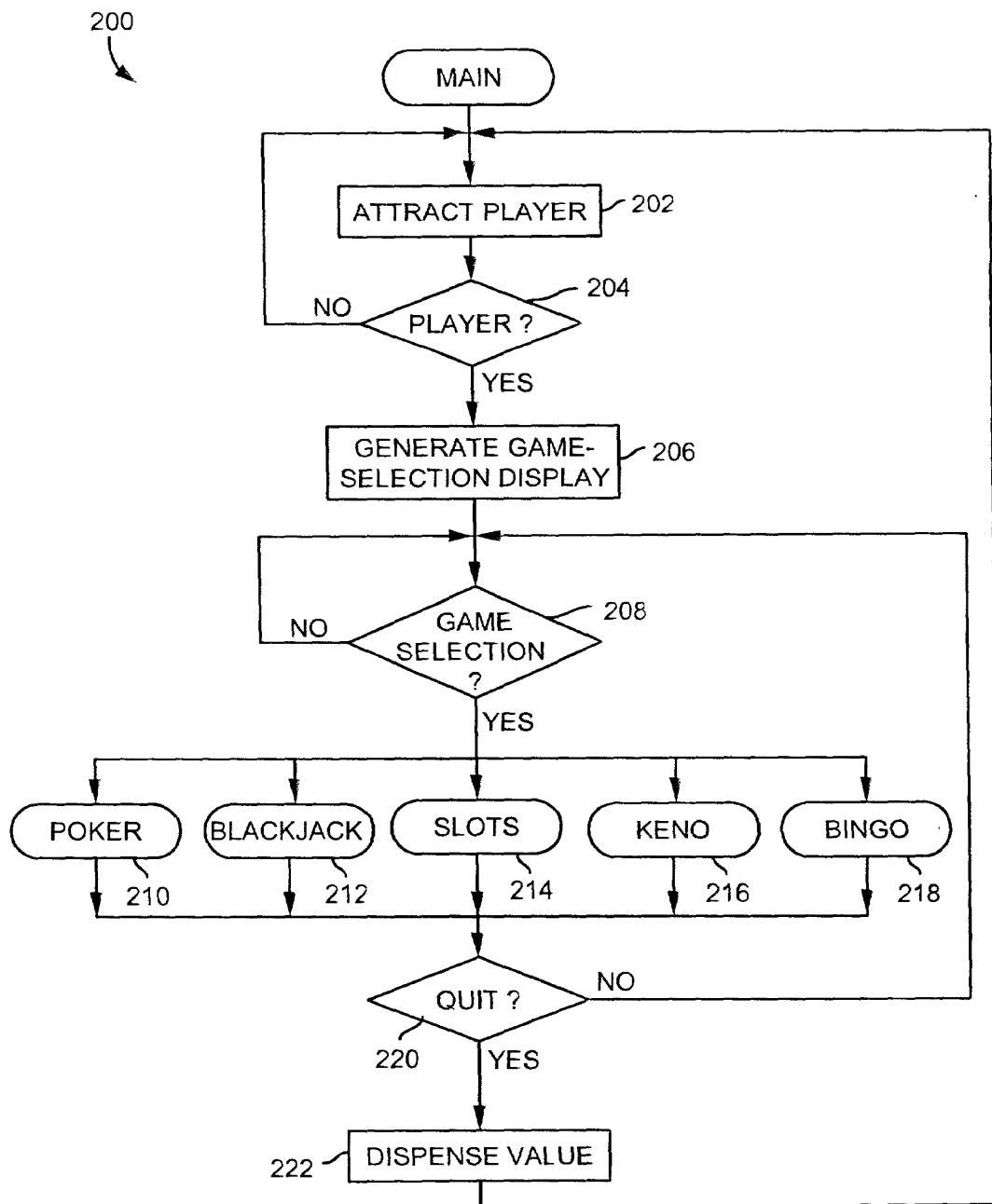


FIG. 7

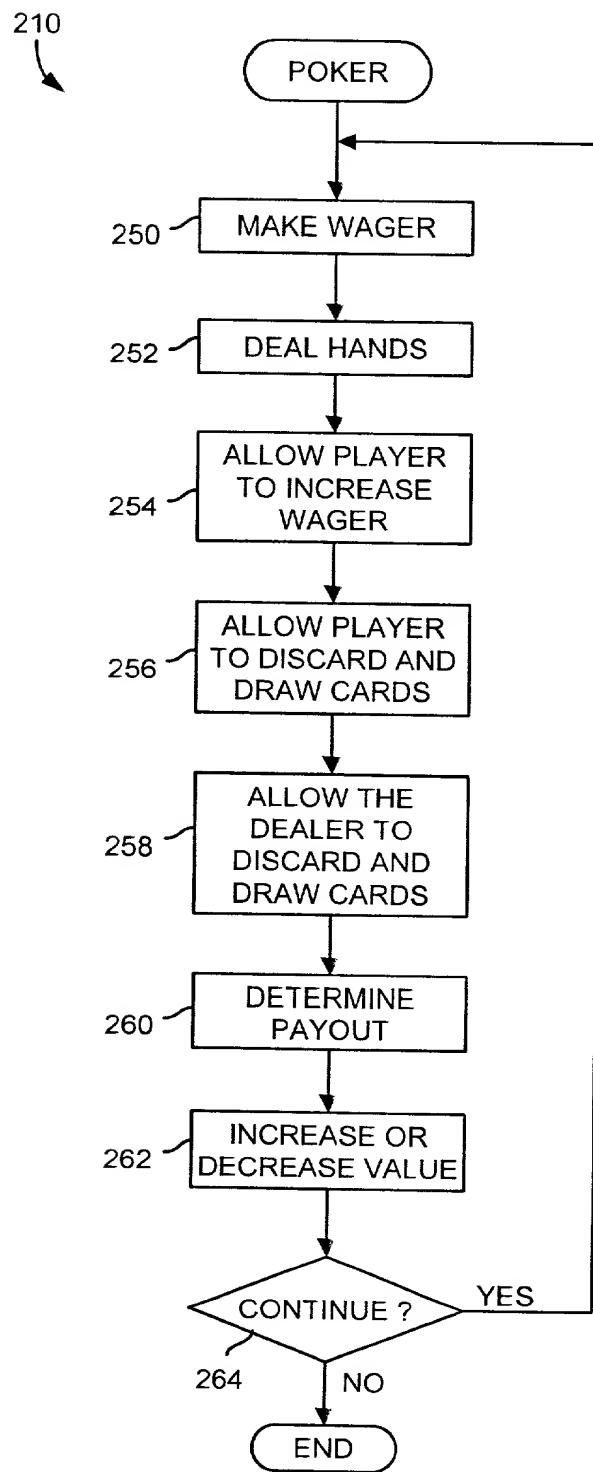


FIG. 8

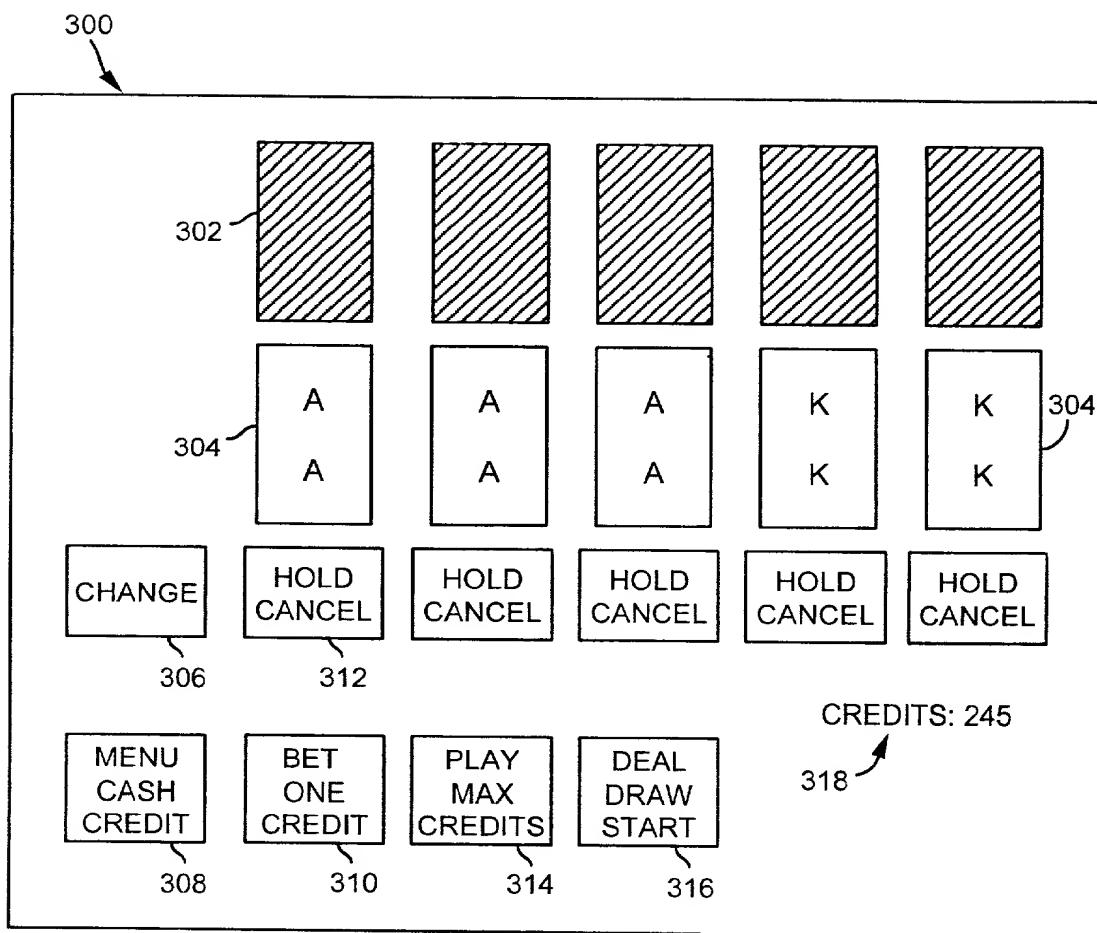


FIG. 9

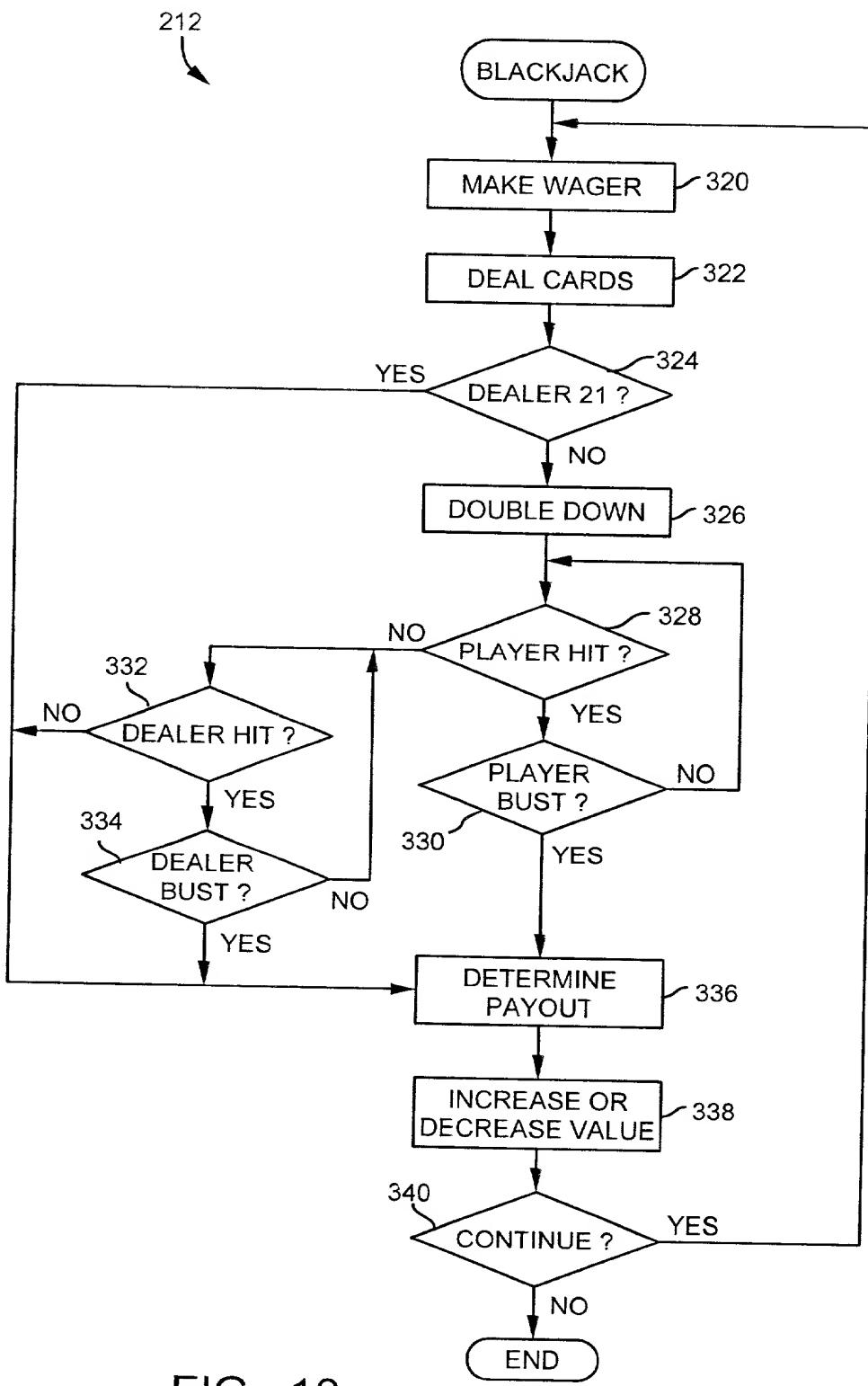


FIG. 10

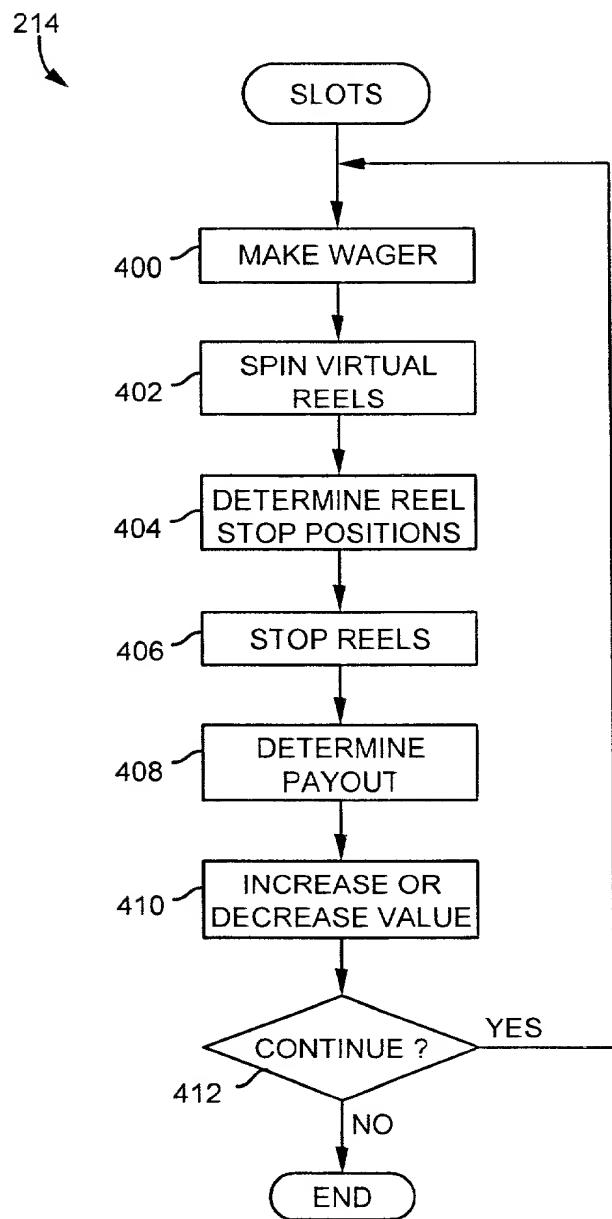


FIG. 11

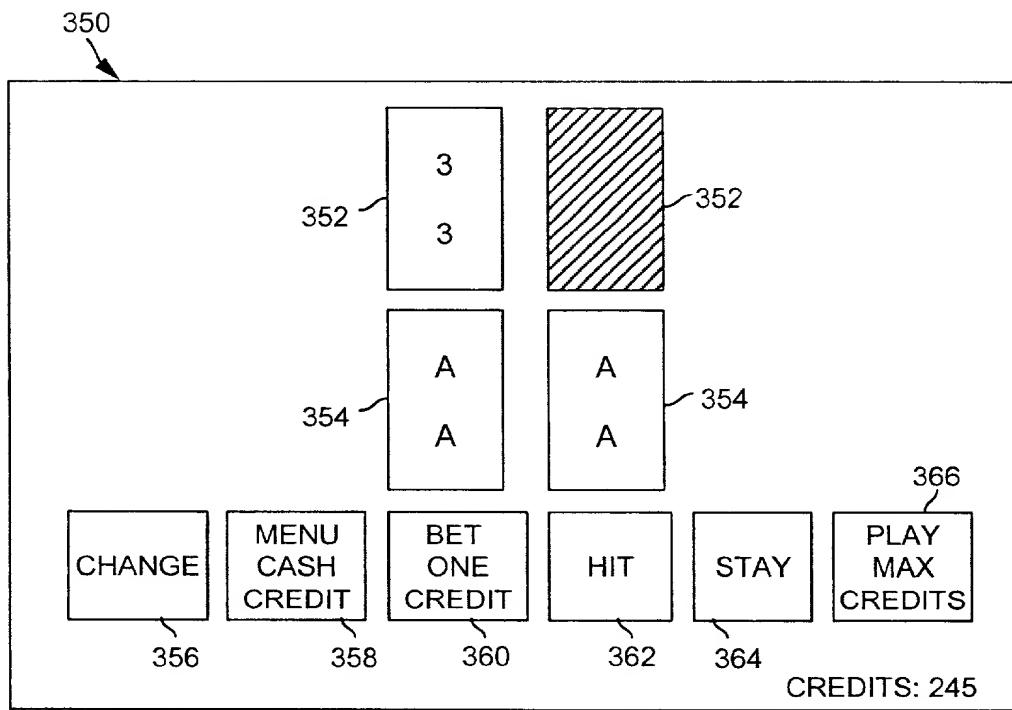


FIG. 12

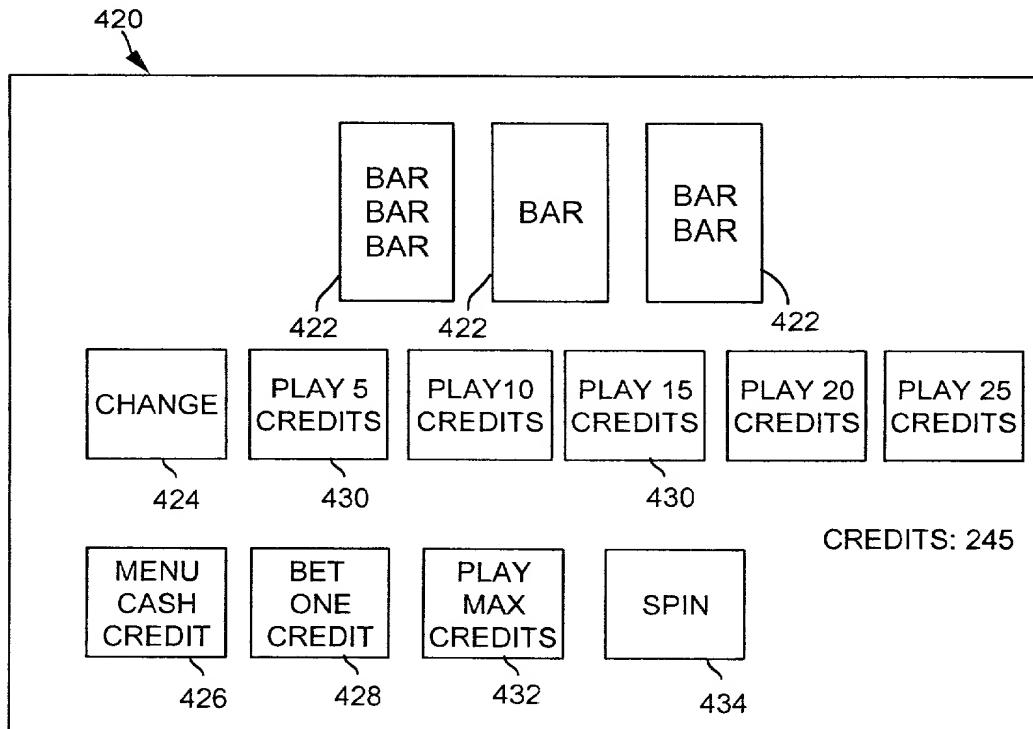


FIG. 13

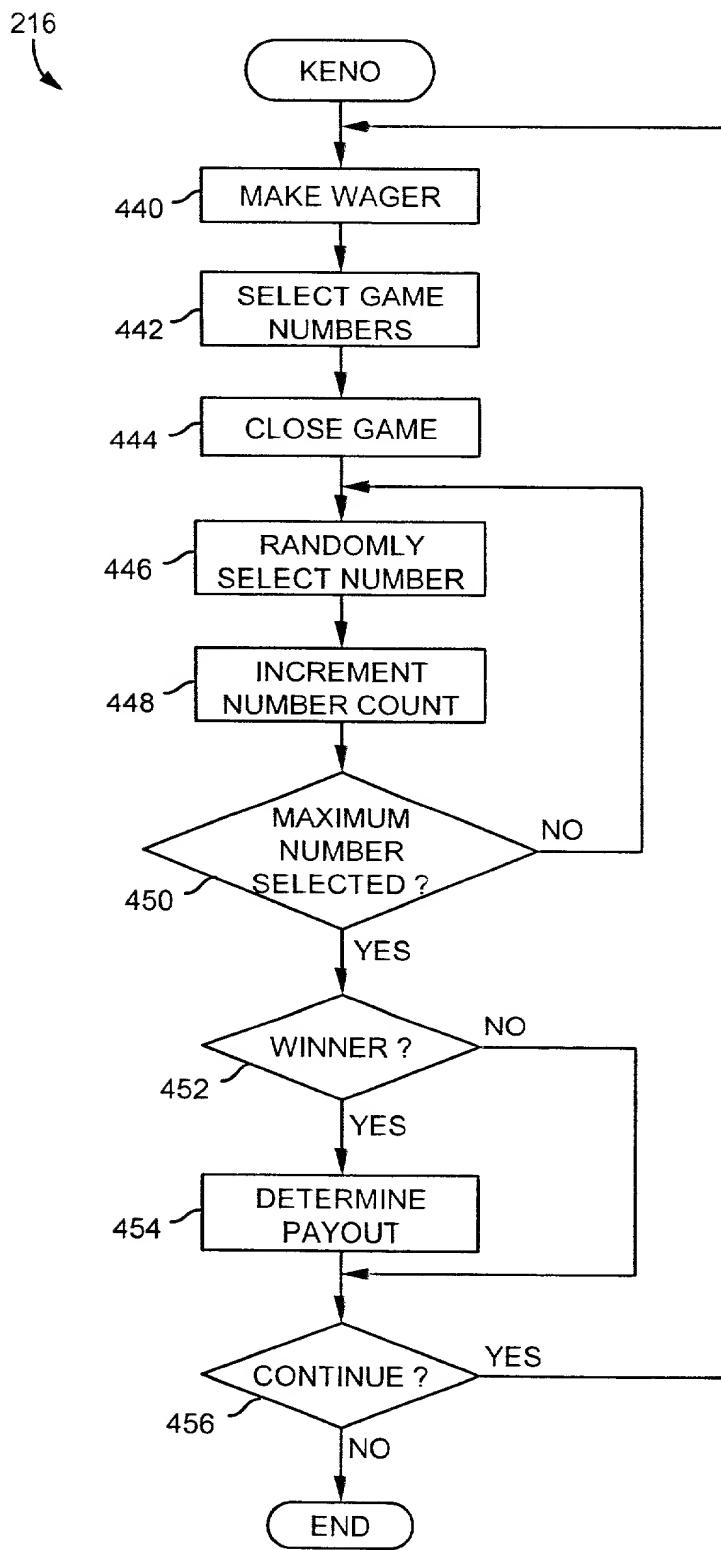


FIG. 14

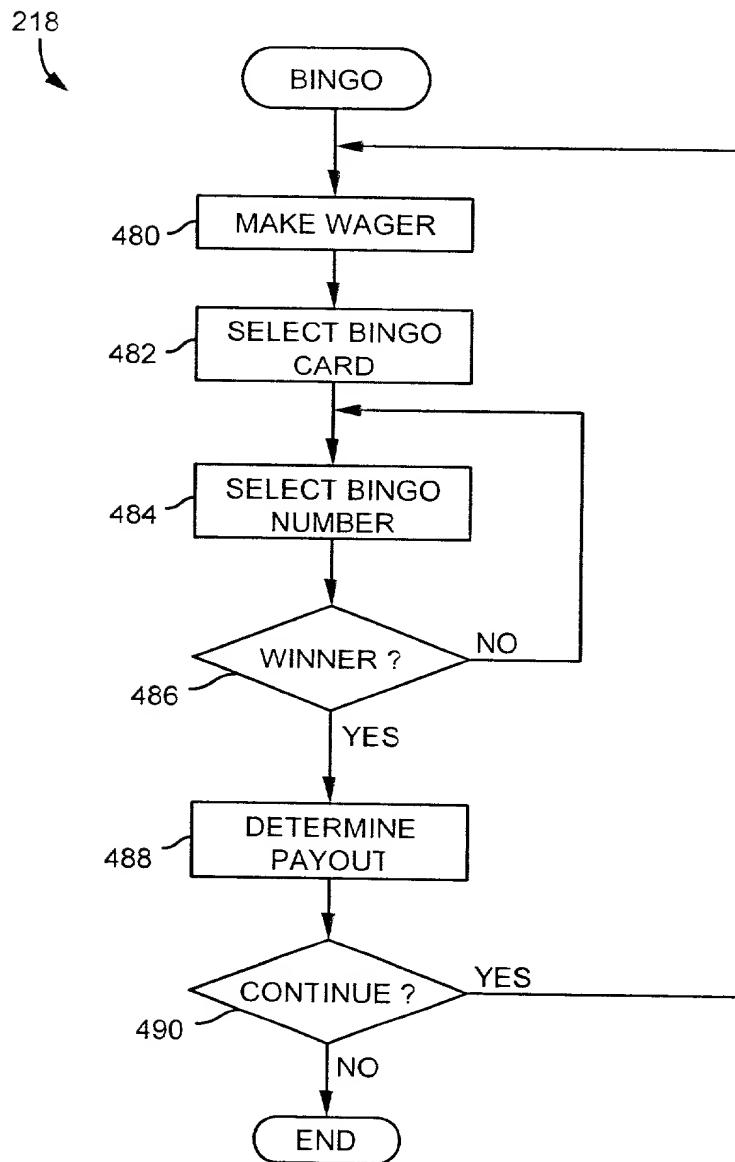


FIG. 15

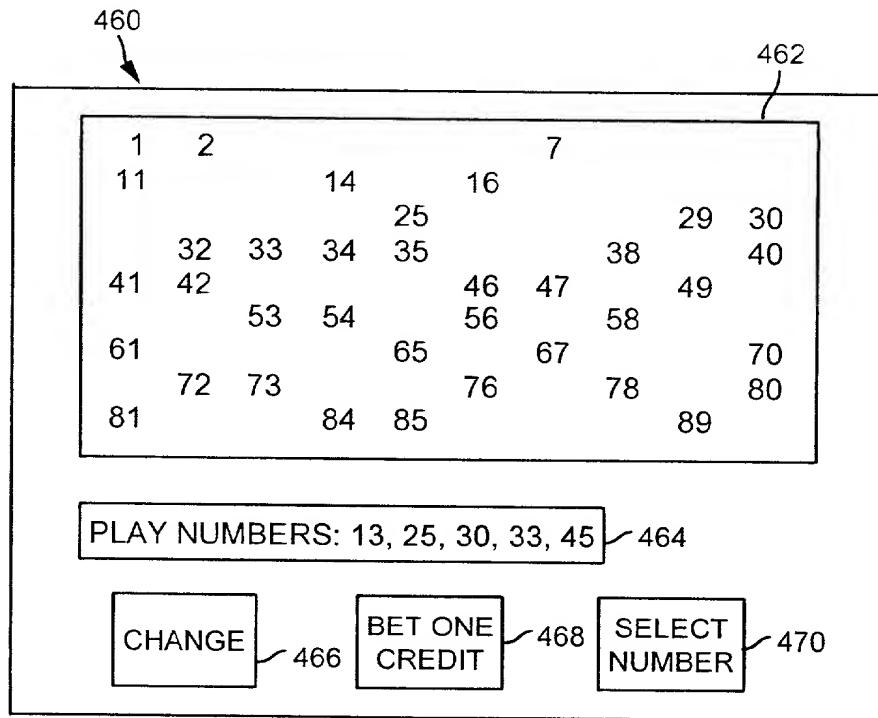


FIG. 16

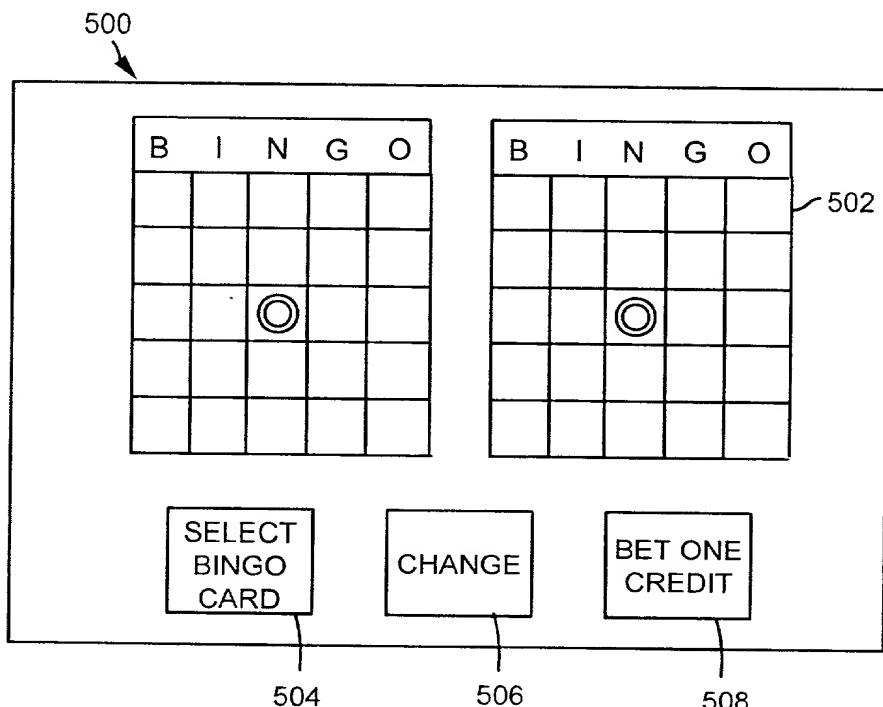


FIG. 17

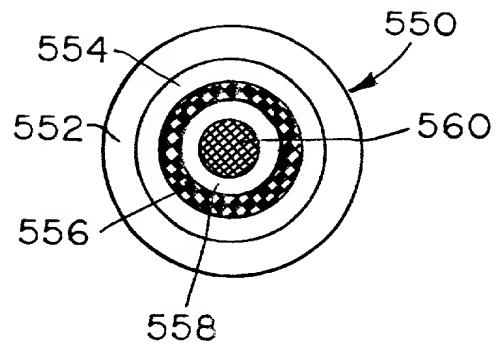


FIG. 18

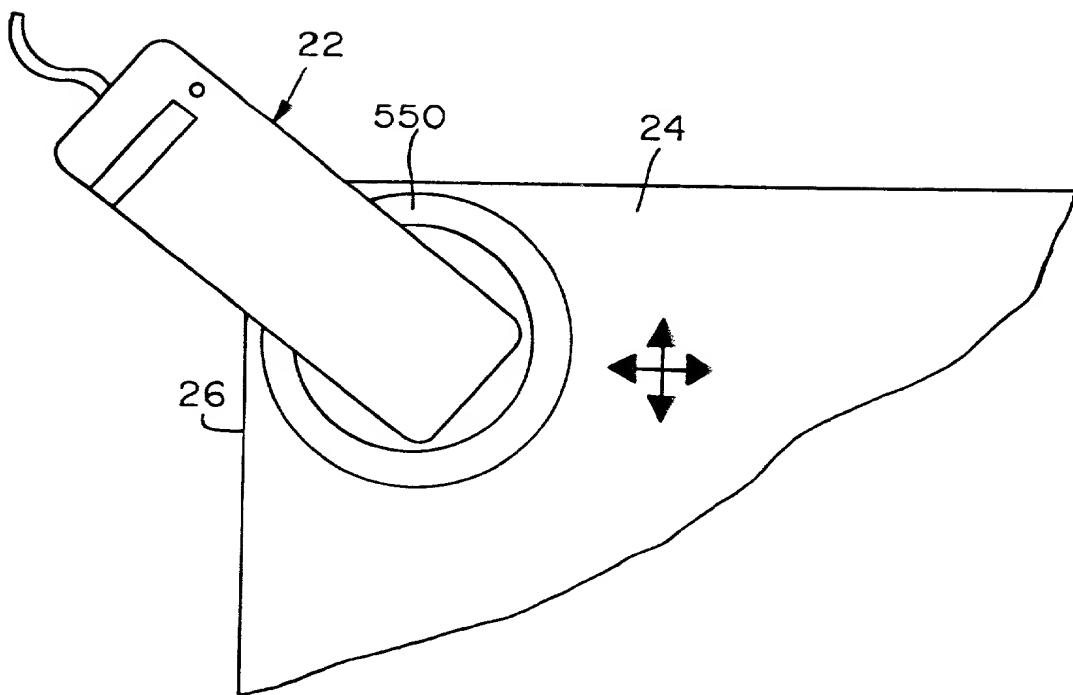


FIG. 19

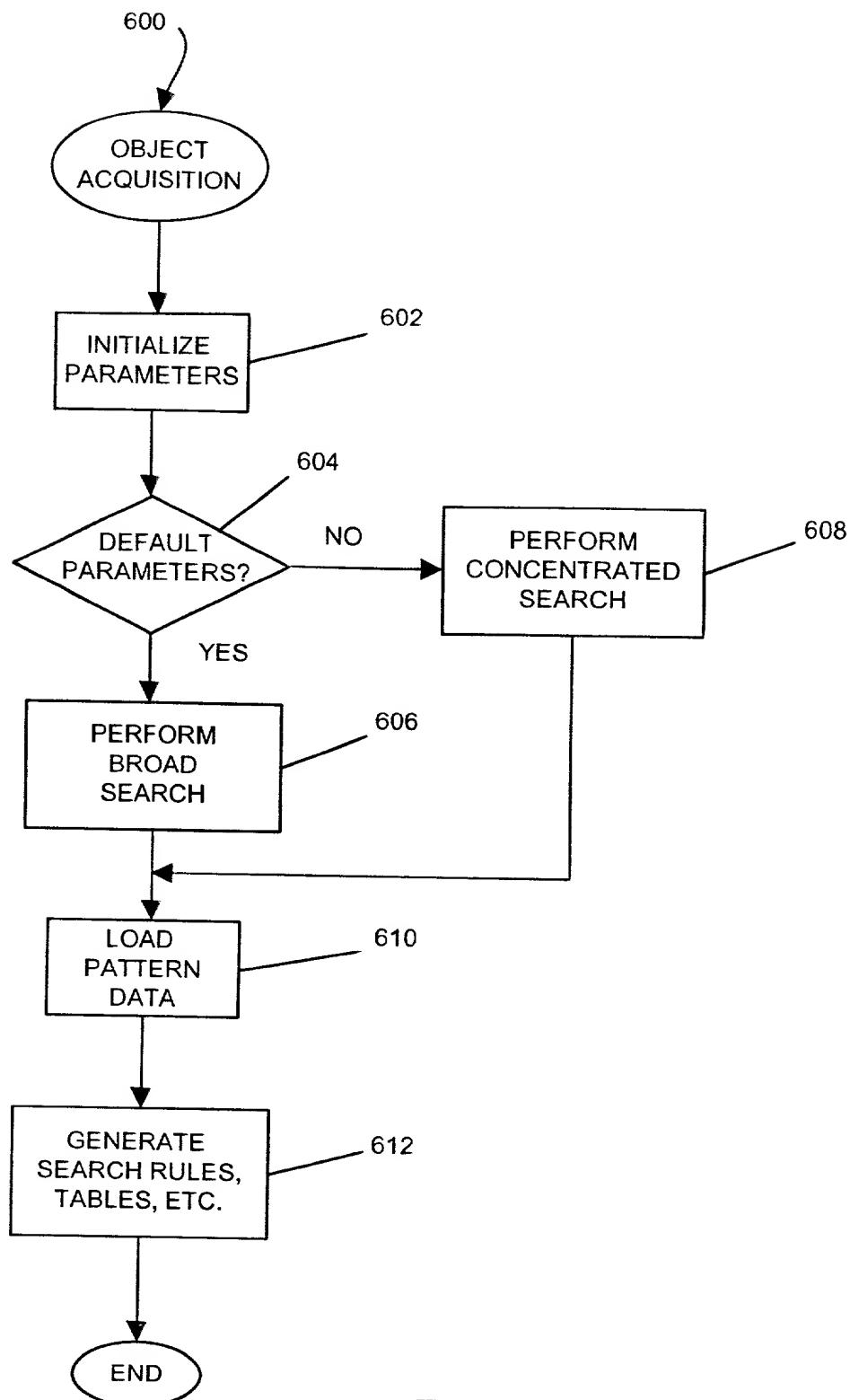


FIG. 20

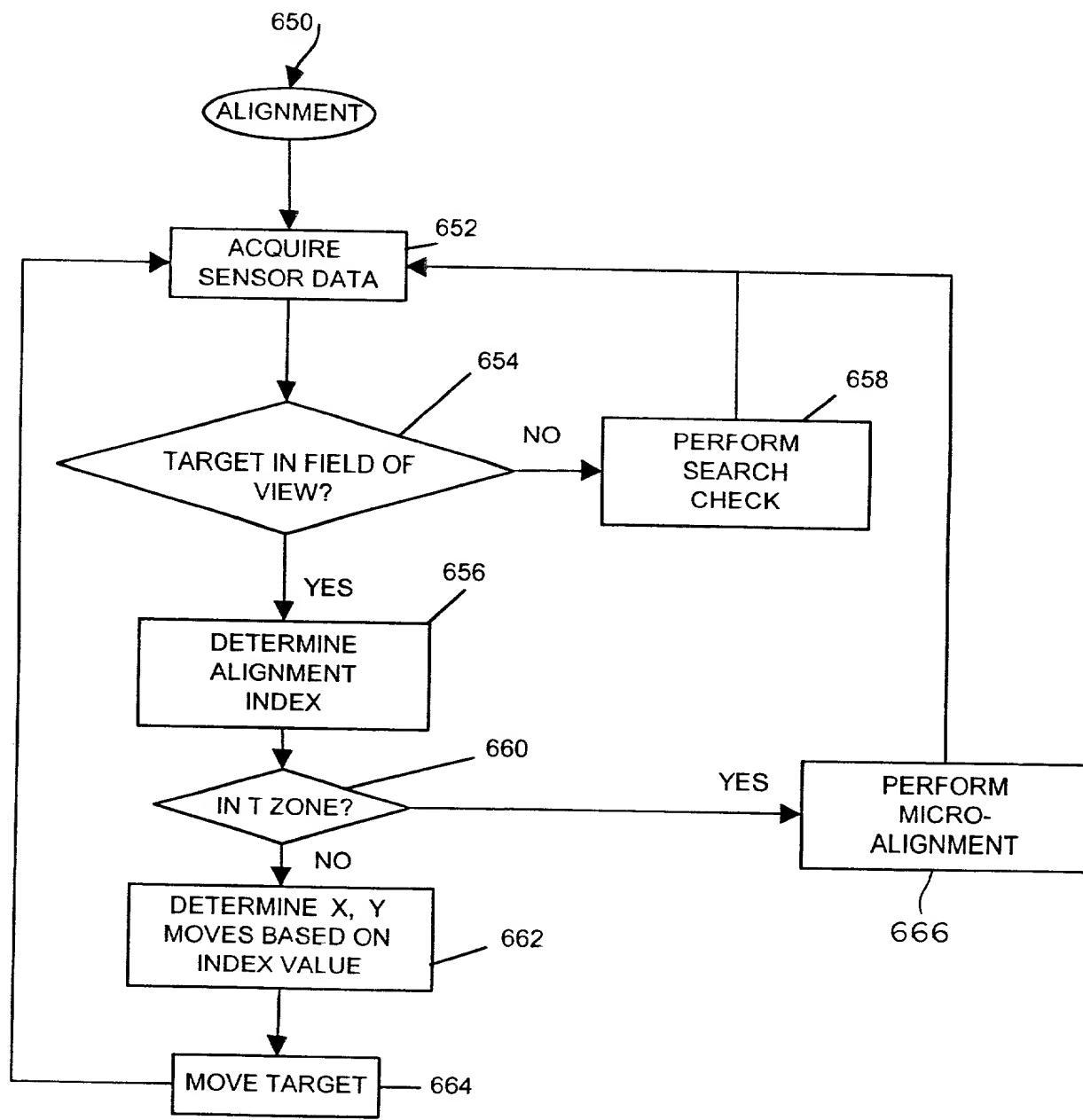


FIG. 21

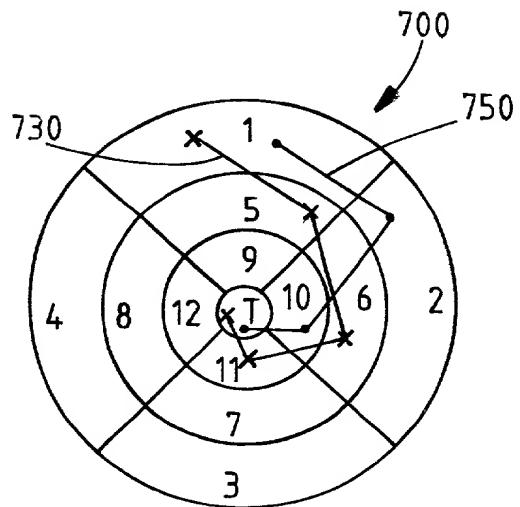


FIG. 22

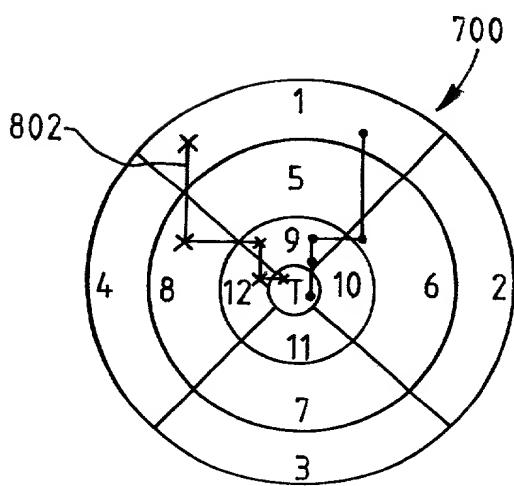


FIG. 24

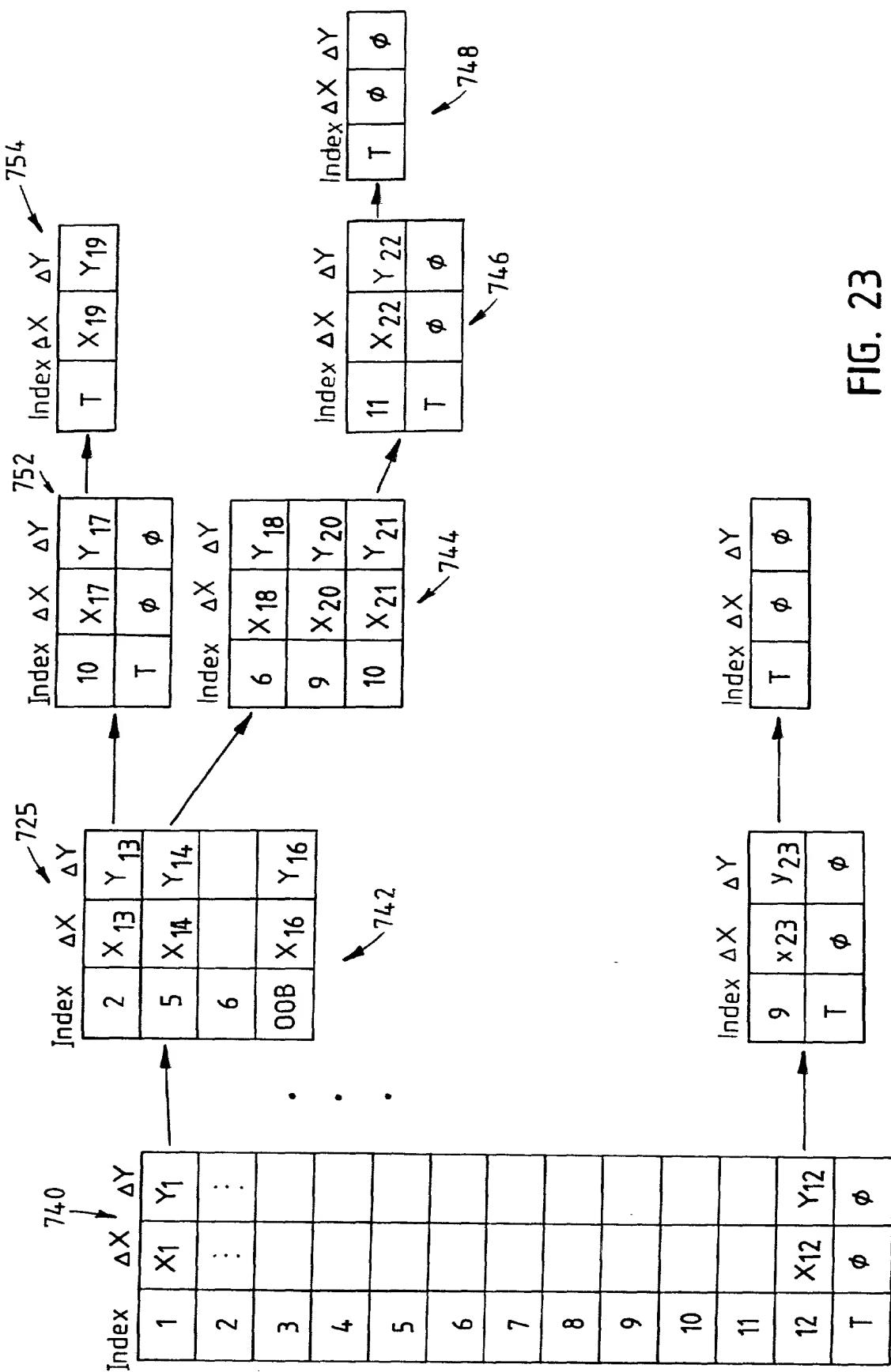


FIG. 23

800

(I)	ΔX	ΔY
1	ϕ	$-Y_1$
2	$-X_1$	ϕ
3	ϕ	Y_1
4	X_1	ϕ
5	ϕ	$-K_1 Y_1$
6	$-K_1 X_1$	ϕ
7	ϕ	$K_1 Y_1$
8	$K_1 X_1$	ϕ
9	ϕ	$-K_2 Y_1$
10	$-K_2 X_1$	ϕ
11	ϕ	$K_2 Y_1$
12	$K_2 X_1$	ϕ

Where: $\phi \leq K_2 \leq K_1 \leq 1$
& Where: X_1 & Y_1 may be dynamically adjusted

FIG. 25